

# On soliton-preserving anti-self-dual Yang-Mills reductions

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March 22nd, 2026

Yamagata Integrable System Workshop

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# The ASDYM equations

The ASDYM equations describe interactions in the gauge field with anti-self-duality, they have the following properties:

- (1) They are 4-d integrable systems
- (2) They possess soliton structure of Wronskian or Grammian
- (3) They can be reduced to many (2+1)-d equations

## Ward's conjecture [Ward-1985]

*... many (and perhaps all?) of the ordinary and partial differential equations that are regarded as being integrable or solvable may be obtained from the self-dual gauge field equations (or its generalizations) by reduction.*

**Our goal:** reduce 4-d ASDYM to some (2+1)-d integrable equations, while the soliton structure can be preserved.

# The ASDYM equations

Let  $G$  be the gauge group and  $\mathfrak{g}$  be its associate Lie algebra. Let  $(z, \tilde{z}, w, \tilde{w})$  be complexified space-time coordinates and  $A_z, A_w \in \mathfrak{g}$  be gauge potentials, the ASDYM equations read as:

$$[\partial_z - \lambda \partial_{\tilde{w}} + A_z, \partial_w - \lambda \partial_{\tilde{z}} + A_w] = 0,$$

where the gauge potentials read as:

$$A_z = \partial_{\tilde{w}} K = -(\partial_z J) J^{-1}, \quad A_w = \partial_{\tilde{z}} K = -(\partial_w J) J^{-1}.$$

The compatible condition leads to two equations:

- (i)  $\partial_{\tilde{z}}((\partial_z J) J^{-1}) - \partial_{\tilde{w}}((\partial_w J) J^{-1}) = 0$  (Yang eqn)
- (ii)  $\partial_z \partial_{\tilde{z}} K - \partial_w \partial_{\tilde{w}} K - [\partial_{\tilde{z}} K, \partial_{\tilde{w}} K] = 0$  (Chalmers-Siegel eqn)

Both of them are regarded as ASDYM equations.

# Darboux transformation

## Vectorial BDT of ASDYM [S.Li-Hamanaka-Huang-Zhang-2025]

Assume  $J^{[0]}$  and  $K^{[0]}$  to be seed solutions that satisfy

$$\begin{aligned} A_z^{[0]} &= \partial_{\tilde{w}} K^{[0]} = -(\partial_z J^{[0]})(J^{[0]})^{-1}, \\ A_w^{[0]} &= \partial_{\tilde{z}} K^{[0]} = -(\partial_w J^{[0]})(J^{[0]})^{-1}. \end{aligned}$$

Suppose  $\eta \in \mathbb{C}_{N \times 2}$  and  $\theta \in \mathbb{C}_{2 \times N}$  satisfy the linear system

$$\begin{aligned} \partial_z \eta - \Xi(\partial_{\tilde{w}} \eta) &= \eta A_z^{[0]}, & \partial_z \theta - (\partial_{\tilde{w}} \theta) \Lambda &= -A_z^{[0]} \theta, \\ \partial_w \eta - \Xi(\partial_{\tilde{z}} \eta) &= \eta A_w^{[0]}, & \partial_w \theta - (\partial_{\tilde{z}} \theta) \Lambda &= -A_w^{[0]} \theta, \end{aligned}$$

where  $\Xi, \Lambda \in \mathbb{C}_{N \times N}$  are spectral parameter matrices.

# Darboux transformation

## Vectorial BDT of ASDYM [LHHZ-2025]

Then we introduce  $\Omega$  determined by associated Sylvester equation

$$\Xi\Omega - \Omega\Lambda = \eta\theta.$$

Finally, the vectorial BDT of ASDYM is given by

$$J = (I - \theta\Omega^{-1}\Xi^{-1}\eta)J^{[0]}, \quad K = \theta\Omega^{-1}\eta + K^{[0]}.$$

The vectorial BDT of ASDYM transforms seed solutions to  $N$ -soliton solutions with different backgrounds.

**Remark:** By setting  $A_z^{[0]} = A_w^{[0]} = 0$ , one can extract **Cauchy matrix structure** from it, which leads to ASDYM bright  $N$ -soliton.

# Soliton solutions of ASDYM

Let  $J^{[0]} = I$  and  $K^{[0]} = 0$ , then  $A_z^{[0]} = A_w^{[0]} = 0$ , and one obtains:

Cauchy matrix structure [S.Li-Qu-Zhang-2023,LHHZ-2025]

Sylvester equation:

$$\Xi\Omega - \Omega\Lambda = \eta\theta.$$

Dispersion relations:

$$\begin{aligned}\partial_z\eta &= \Xi(\partial_{\bar{w}}\eta), & \partial_z\theta &= (\partial_{\bar{w}}\theta)\Lambda, \\ \partial_w\eta &= \Xi(\partial_{\bar{z}}\eta), & \partial_w\theta &= (\partial_{\bar{z}}\theta)\Lambda,\end{aligned}$$

Explicit solutions:

$$J = I - \theta\Omega^{-1}\Xi^{-1}\eta, \quad K = \theta\Omega^{-1}\eta.$$

# Soliton solutions of ASDYM

Suppose the spectral parameter matrices are both diagonal, then the Cauchy matrix structure is satisfied by the following construction [Ohta-2024]:

$$\begin{aligned}\Xi &= \text{Diag}(\xi_1, \dots, \xi_N), & \eta &= (\phi_{is}(\xi_i z + \tilde{w}, \xi_i w + \tilde{z}))_{N \times 2}, \\ \Lambda &= \text{Diag}(\lambda_1, \dots, \lambda_N), & \theta &= (\psi_{sj}(\lambda_j z + \tilde{w}, \lambda_j w + \tilde{z}))_{2 \times N}, \\ \Omega &= (\Omega_{ij})_{N \times N}, & \Omega_{ij} &= \frac{\sum_{s=1}^2 \phi_{is} \psi_{sj}}{\xi_i - \lambda_j},\end{aligned}$$

where  $\phi_{is}$  and  $\psi_{sj}$  are arbitrary functions. If  $\phi_{is}$  and  $\psi_{sj}$  are exponential functions, it gives rise to soliton solution:

$$\phi_{is} = A_{is} \exp(\alpha_{is}(\xi_i z + \tilde{w}) + \beta_{is}(\xi_i w + \tilde{z})), \quad (1a)$$

$$\psi_{sj} = B_{sj} \exp(\gamma_{sj}(\lambda_j z + \tilde{w}) + \delta_{sj}(\lambda_j w + \tilde{z})). \quad (1b)$$

# Reduction to (2+1)-d integrable systems

Let  $G = GL(2)$ , the  $J$ -matrix and  $K$ -matrix can be decomposed to

$$J = \begin{pmatrix} J_{11} & J_{12} \\ J_{21} & J_{22} \end{pmatrix}, \quad K = \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix}.$$

To reduce 4-d system to (2+1)-d system, and without losing any generalities, we assume the  $\tilde{w}$ -derivative can be eliminated after applying the following condition:

$$\partial_{\tilde{w}} K = [K, \frac{1}{2}\sigma_3], \quad \sigma_3 := \text{Diag}(1, -1). \quad (2)$$

**Remark:** It can be achieved by following setting in (1)

$$\alpha_{i1} = \frac{1}{2}, \quad \alpha_{i2} = -\frac{1}{2}, \quad \gamma_{1j} = -\frac{1}{2}, \quad \gamma_{2j} = \frac{1}{2},$$

# The (2+1)-d NLS equation

In this sense, the Chalmers-Siegel equation simplifies to

$$\partial_z \partial_{\bar{z}} K - [\partial_w K, \frac{1}{2} \sigma_3] - [\partial_{\bar{z}} K, [K, \frac{1}{2} \sigma_3]] = 0.$$

Expanding it in terms of matrix entries, one obtains

$$\begin{aligned} K_{11} &= \partial_z^{-1}(K_{12}K_{21}), & K_{22} &= -\partial_z^{-1}(K_{21}K_{12}), \\ \partial_z \partial_{\bar{z}} K_{12} &= -\partial_w K_{12} - (\partial_{\bar{z}} K_{11})K_{12} + K_{12}(\partial_{\bar{z}} K_{22}), \\ \partial_z \partial_{\bar{z}} K_{21} &= \partial_w K_{21} + (\partial_{\bar{z}} K_{22})K_{21} - K_{21}(\partial_{\bar{z}} K_{11}). \end{aligned}$$

Defining  $(r, q) := (K_{21}, -K_{12})$ , it yields the (2+1)-d NLS system:

$$r_w = r_{z\bar{z}} - 2r\partial_z^{-1}(qr)_{\bar{z}}, \quad (\text{NLS-1})$$

$$q_w = -q_{z\bar{z}} + 2q\partial_z^{-1}(rq)_{\bar{z}}, \quad (\text{NLS-2})$$

# The (2+1)-d NLS equation

Define  $(x, y, t) := (iz, i\tilde{z}, i\tilde{w})$ , and introduce  $u := r = q^*$ , then (2+1)-d NLS system becomes the (2+1)-d NLS equation:

$$iu_t + u_{xy} + 2u\partial_x^{-1}(|u|^2)_y = 0.$$

**Remark:** Similar reductions are revealed in KP reduction, relative ASDYM reduction are discussed [[Kakei-Ikeda-Takasaki-2001](#)].

**Remark:** The bilinear NLS can be obtained from bilinear ASDYM [[Sasa-Ohta-Matsukidaira-1998](#)].

From 4-d ASDYM to (2+1)-d NLS

$$\text{4-d ASDYM equation} \xrightarrow[\begin{matrix} \partial_{\tilde{w}} K = [K, \frac{1}{2}\sigma_3] \\ (r, q) := (K_{21}, -K_{12}) \end{matrix}]{\hspace{1cm}} \text{(2+1)-d NLS system}$$

# The (2+1)-d NLS equation

Since

$$K = \theta \Omega^{-1} \eta = \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} \Omega^{-1} (\eta_1 \quad \eta_2) = \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix},$$

thus we have

$$q = -K_{12} = -\theta_1 \Omega^{-1} \eta_2, \quad r = K_{21} = \theta_2 \Omega^{-1} \eta_1.$$

The conjugate reduction is given by ( $A^\dagger = (A^*)^T$ ):

$$\Lambda = \Xi^\dagger, \quad \theta_1 = \eta_1^\dagger, \quad \theta_2 = \eta_2^\dagger, \quad \Omega = -\Omega^\dagger,$$

which leads to

$$q = -\eta_1^\dagger \Omega^{-1} \eta_2 = (\eta_2^\dagger \Omega^{-1} \eta_1)^\dagger = r^*.$$

# The (2+1)-d GI equation

Reduction to (2+1)-d GI (Gerdjikov-Ivanov) is based on the result of (2+1)-d NLS. Starting from (2), we have

$$(\partial_z J)J^{-1} = \partial_{\tilde{w}} K = [K, \frac{1}{2}\sigma_3],$$

which indicates

$$\begin{pmatrix} \partial_z J_{11} & \partial_z J_{12} \\ \partial_z J_{21} & \partial_z J_{22} \end{pmatrix} = \begin{pmatrix} K_{12}J_{21} & K_{12}J_{22} \\ -K_{21}J_{11} & -K_{21}J_{12} \end{pmatrix}.$$

Let  $(p, q, r) = (J_{21}J_{11}^{-1}, -K_{12}, K_{21})$ , they yield the relation:

$$p_z = -r + p^2 q. \quad (\text{MT})$$

**This Miura Transformation links NLS  $(r, q)$  and GI  $(p, q)$ !**

# The (2+1)-d GI equation

From the second equation of NLS system

$$q_w = -q_{z\bar{z}} + 2q\partial_z^{-1}(rq)_{\bar{z}}, \quad (\text{NLS-2})$$

we substitute  $r = -p_z + p^2q$  into it, which gives rise to

$$q_w = -q_{z\bar{z}} - 2q\partial_z^{-1}(p_zq)_{\bar{z}} + 2q\partial_z^{-1}(p^2q^2)_{\bar{z}}. \quad (\text{GI-2})$$

On the other hand, the  $w$ -derivative of (MT) shows

$$r_w = (2pq - \partial_z)p_w + p^2q_w,$$

which along with (NLS-1) and (NLS-2) indicates an equation of:

$$p_w = p_{z\bar{z}} - 2p\partial_z^{-1}(pq_z)_{\bar{z}} - 2p\partial_z^{-1}(p^2q^2)_{\bar{z}}. \quad (\text{GI-1})$$

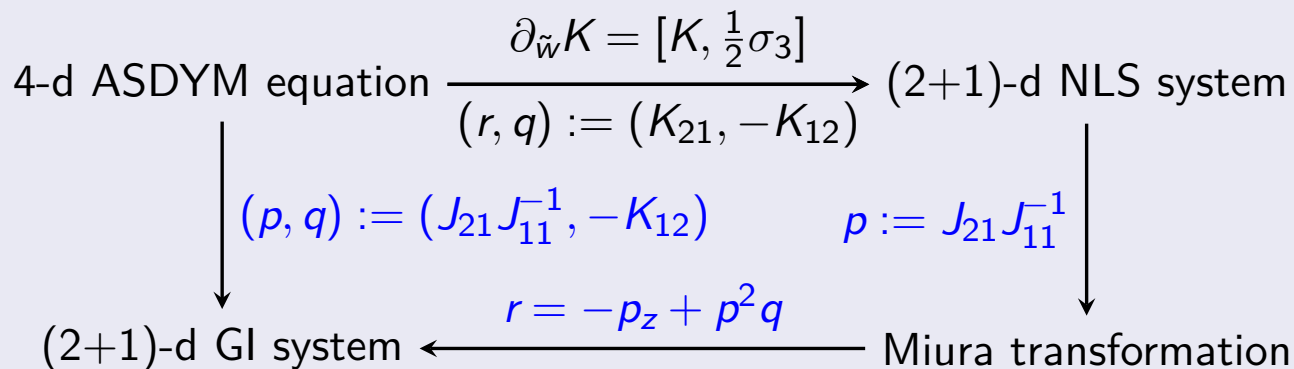
# The (2+1)-d GI equation

Define  $(x, y, t) := (iz, i\tilde{z}, i\tilde{w})$ , and introduce  $u := p = q^*$ , then (2+1)-d GI system becomes the (2+1)-d GI equation:

$$iu_t + u_{xy} + 2iu\partial_x^{-1}(uu_x^*)_y + 2u\partial_x^{-1}(|u|^4)_y = 0.$$

The relation between ASDYM and NLS and GI are summarized:

## From 4-d ASDYM to (2+1)-d GI



# The (2+1)-d GDNLS equation

Other than GI equation, the DNLS equations are known to have three types, the Kaup-Newell type and the Chen-Lee-Liu type. They are linked through gauge transformation [Wadati-Sogo-1983]. Moreover, the three equations can be viewed in one generalized DNLS equation [Kundu-1984,1987].

## Gauge transformation and GDNLS equation

Let  $u_{[\text{GDNLS}]} = u_{[\text{GI}]}s^\gamma$ ,  $s = \exp(i\partial_x^{-1}|u_{[\text{GI}]}|^2)$ , then  $u_{[\text{GDNLS}]}$  yields:

$$\begin{aligned}
 iu_t + u_{xy} - i\gamma u\partial_x^{-1}(u_x u^*)_y - i\gamma u_x\partial_x^{-1}(|u|^2)_y & \quad (\text{GDNLS}) \\
 + 2i(\gamma - 1)u\partial_x^{-1}(uu_x^*)_y + (\gamma - 1)(\gamma - 2)u\partial_x^{-1}(|u|^4)_y & = 0.
 \end{aligned}$$

When  $\gamma = 0, 1, 2$ , (GDNLS) becomes GI, CLL, KN, respectively.

# The (2+1)-d GDNLS equation

## Realization of gauge factor in ASDYM reduction:

$$s = \exp(-\partial_z^{-1}(qp)) = \exp(\partial_z^{-1}(\ln(J_{11})_z)) = J_{11}.$$

**Construction of (2+1)-d GDNLS:** Suppose  $(p, q)$  satisfies (2+1)-d GI system, by defining  $(u, v) = (ps^\gamma, qs^{-\gamma})$ , it yields

$$\begin{aligned} u_w = u_{z\bar{z}} + \gamma u \partial_z^{-1}(u_z v)_{\bar{z}} + \gamma u_z \partial_z^{-1}(uv)_{\bar{z}} & \quad (\text{GDNLS-1}) \\ + 2(\gamma - 1)u \partial_z^{-1}(uv_z)_{\bar{z}} - (\gamma - 1)(\gamma - 2)u \partial_z^{-1}(u^2 v^2)_{\bar{z}}, & \end{aligned}$$

$$\begin{aligned} v_w = -v_{z\bar{z}} + \gamma v \partial_z^{-1}(uv_z)_{\bar{z}} + \gamma v_z \partial_z^{-1}(uv)_{\bar{z}} & \quad (\text{GDNLS-2}) \\ + 2(\gamma - 1)v \partial_z^{-1}(u_z v)_{\bar{z}} + (\gamma - 1)(\gamma - 2)v \partial_z^{-1}(u^2 v^2)_{\bar{z}}. & \end{aligned}$$

Define  $(x, y, t) := (iz, i\bar{z}, i\tilde{w})$ , and assume  $v = u^*$ , the (2+1)-d GDNLS system becomes **(GDNLS)**.

# The (2+1)-d GDNLS equation

Let  $\gamma = 1$ , defining  $(\tilde{p}, \tilde{q}) = (ps, qs^{-1})$ , it yields (2+1)-d CLL:

$$\tilde{p}_w = \tilde{p}_{z\bar{z}} + \tilde{p}\partial_z^{-1}(\tilde{p}_z\tilde{q})_{\bar{z}} + \tilde{p}_z\partial_z^{-1}(\tilde{p}\tilde{q})_{\bar{z}}, \quad (\text{CLL-1})$$

$$\tilde{q}_w = -\tilde{q}_{z\bar{z}} + \tilde{q}\partial_z^{-1}(\tilde{p}\tilde{q}_z)_{\bar{z}} + \tilde{q}_z\partial_z^{-1}(\tilde{p}\tilde{q})_{\bar{z}}. \quad (\text{CLL-2})$$

Let  $\gamma = 2$ , defining  $(\hat{p}, \hat{q}) = (ps^2, qs^{-2})$ , it yields (2+1)-d KN:

$$\hat{p}_w = \hat{p}_{z\bar{z}} + 2(\hat{p}\partial_z^{-1}(\hat{p}\hat{q})_{\bar{z}})_z, \quad (\text{KN-1})$$

$$\hat{q}_w = -\hat{q}_{z\bar{z}} + 2(\hat{q}\partial_z^{-1}(\hat{p}\hat{q})_{\bar{z}})_z. \quad (\text{KN-2})$$

The construction of three DNLS equations are summarized:

## Realization of DNLS in ASDYM reduction

- (2+1)-d **GI**:  $(p, q) = (J_{21}J_{11}^{-1}, -K_{12})$
- (2+1)-d **CLL**:  $(\tilde{p}, \tilde{q}) = (ps, qs^{-1}) = (J_{21}, -J_{11}^{-1}K_{12})$
- (2+1)-d **KN**:  $(\hat{p}, \hat{q}) = (ps^2, qs^{-2}) = (J_{21}J_{11}, -J_{11}^{-2}K_{12})$



# The (2+1)-d GDNLS equation

To achieve the conjugate condition of GDNLS  $(u, v)$ , we first consider the case of GI  $(p, q)$ , where:

$$p = \frac{J_{21}}{J_{11}} = -\frac{\theta_2 \Omega^{-1} \Xi^{-1} \eta_1}{1 - \theta_1 \Omega^{-1} \Xi^{-1} \eta_1}, \quad q = -K_{12} = -\theta_1 \Omega^{-1} \eta_2.$$

The conjugate condition is given by [\[S.Li-Liu-Zhang-2025\]](#):

$$\Lambda = \Xi^\dagger, \quad \theta_1 = \eta_1^\dagger, \quad \theta_2 = -\eta_2^\dagger \Xi^\dagger, \quad \Xi \Omega + \Omega^\dagger \Xi^\dagger = \eta_1 \eta_1^\dagger.$$

Through a direct calculation we have  $p = q^*$ :

$$K_{12}^\dagger J_{11} = \eta_2^\dagger \Omega^{-\dagger} \eta_1 - \eta_2^\dagger (\Omega^{-\dagger} \Xi + \Xi^\dagger \Omega^{-1}) \Xi^{-1} \eta_1 = -J_{21},$$

# The (2+1)-d GDNLS equation

As for the gauge factor  $s = J_{11}$ , it yields  $s^* = s^{-1}$ :

$$\begin{aligned}
 J_{11} J_{11}^\dagger &= (1 - \eta_1^\dagger \Omega^{-1} \Xi^{-1} \eta_1)(1 - \eta_1^\dagger \Xi^{-\dagger} \Omega^{-\dagger} \eta_1) \\
 &= 1 - \eta_1^\dagger (\Omega^{-1} \Xi^{-1} + \Xi^{-\dagger} \Omega^{-\dagger}) \eta_1 + \eta_1^\dagger \Omega^{-1} \Xi^{-1} \eta_1 \eta_1^\dagger \Xi^{-\dagger} \Omega^{-\dagger} \eta_1 \\
 &= 1 - \eta_1^\dagger (\Omega^{-1} \Xi^{-1} + \Xi^{-\dagger} \Omega^{-\dagger} - \Omega^{-1} \Xi^{-1} - \Xi^{-\dagger} \Omega^{-\dagger}) \eta_1 = 1.
 \end{aligned}$$

Thus  $v^* = (s^{-\gamma} q)^* = s^\gamma p = u$ , and it solves the GDNLS equation.

# The (2+1)-d GDNLS equation

The relations between ASDYM, NLS and KN were revealed by using bilinear transformation [SOM-1998]:

- **(2+1)-d NLS:**  $i\partial_T\psi + \partial_X\partial_Y\psi + 2\psi\partial_X^{-1}\partial_Y|\psi|^2 = 0$

$$\psi = \frac{\tau_{n-1,m-1}}{\tau_{n,m}}, \quad \psi^* = \frac{\tau_{n+1,m+1}}{\tau_{n,m}}. \quad (\text{BT-NLS})$$

- **(2+1)-d KN:**  $i\partial_T\psi + \partial_X\partial_Y\psi + 2i\partial_X[\psi\partial_X^{-1}\partial_Y|\psi|^2] = 0$

$$\psi^* = \frac{-i\tau_{n-1,m}\tau_{n,m+1}}{\tau_{n,m}^2}, \quad \psi = \frac{\tau_{n,m}\tau_{n+1,m+1}}{\tau_{n,m+1}^2}. \quad (\text{BT-KN})$$

**Remark:** The above notations (equations) are from the original paper of [SOM-1998], we are interested in their bilinear forms.

# The (2+1)-d GDNLS equation

The  $J$ -matrix and  $K$ -matrix have their bilinear transformations  
[Ohta-2024,LLZ-2025]:

$$J_{ij} = g_{ij}/f, \quad K_{ij} = h_{ij}/f, \quad 1 \leq i, j \leq 2.$$

In this sense, we have

- **BT of NLS from**  $(r, q) = (K_{21}, -K_{12})$ :

$$r = \frac{h_{21}}{f}, \quad q = -\frac{h_{12}}{f}. \quad (\text{BT-NLS-new})$$

- **BT of KN from**  $(\hat{p}, \hat{q}) = (J_{21}J_{11}, -J_{11}^{-2}K_{12})$ :

$$\hat{p} = \frac{g_{11}g_{21}}{f^2}, \quad \hat{q} = -\frac{fh_{12}}{g_{11}^2}. \quad (\text{BT-KN-new})$$

# The (2+1)-d GDNLS equation

The BT of GDNLS are given in [Kakei-Sasa-Satsuma-1995]:

- **BT of GDNLS (KSS version):**

$$v = \frac{\tilde{f}^{\gamma-1} \tilde{g}}{f^\gamma}, \quad u = \frac{f^{\gamma-1} g}{\tilde{f}^\gamma} \quad (\text{BT-GDNLS})$$

- **BT of GDNLS from  $(u, v) = (J_{21} J_{11}^{\gamma-1}, -J_{11}^{-\gamma} K_{12})$ :**

$$u = \frac{g_{11}^{\gamma-1} g_{21}}{f^\gamma}, \quad v = -\frac{f^{\gamma-1} h_{12}}{g_{11}^\gamma}. \quad (\text{BT-GDNLS-new})$$

The BT of GDNLS from ASDYM yields KSS construction, and also gives rise to the BTs of GI, CLL, KN and FL (Fokas-Lenells) [Nakamura-Chen-1980, Liu-Wang-Zhang-2022].

# Concluding remarks

Starting from  $J$ -matrix and  $K$ -matrix of GL(2) ASDYM equations, the structure of (2+1)-d NLS and GDNLS are clear.

## Main theorem of this talk

Suppose  $\Xi, \Lambda, \Omega, \eta = (\eta_1, \eta_2), \theta^T = (\theta_1^T, \theta_2^T)$  satisfy the Cauchy matrix structure of ASDYM [SQZ-2023], define

$$J_{11} = 1 - \theta_1 \Omega^{-1} \Xi^{-1} \eta_1, \quad J_{21} = -\theta_2 \Omega^{-1} \Xi^{-1} \eta_1,$$

$$K_{12} = \theta_1 \Omega^{-1} \eta_2, \quad K_{21} = \theta_2 \Omega^{-1} \eta_1.$$

Then NLS, GI and GDNLS are solved by ASDYM solitons:

- (2+1)-d **NLS**:  $(K_{21}, -K_{12})$
- (2+1)-d **GI**:  $(J_{21} J_{11}^{-1}, -K_{12})$
- (2+1)-d **GDNLS**:  $(J_{21} J_{11}^{\gamma-1}, -J_{11}^{-\gamma} K_{12})$

# Concluding remarks

**Remark 1:** The gauge factor  $s$  between DNLS equations, are usually very difficult to calculate, thus GI, CLL, KN are usually discussed separately. However, in ASDYM reduction, the gauge factor are given by  $J_{11} = 1 - \theta_1 \Omega^{-1} \Xi^{-1} \eta_1$ , it has a very clear expression.

**Remark 2:** By considering higher flows of ASDYM, the ASDYM reduction can be extended to investigate integrable hierarchies, e.g., the AKNS hierarchy, the DNLS hierarchies. [Will appear in our coming research soon...]

**Remark 3:** By considering  $GL(N)$  ASDYM, the ASDYM reduction can be extended to investigate matrix integrable system. [Will appear in our coming research soon...]

# Concluding remarks

**Question 1:** The rogue wave pattern of NLS and GDNLS are investigated by bilinear method in [Yang-Yang-2021,2023], and ASDYM have rogue wave solution [Ohta-2024]. Can ASDYM rogue wave gives rise to NLS/GDNLS rogue wave?

**Question 2:** KP reduction is a powerful method, have been applied to investigate NLS [KIT-2001] and GDNLS [YY-2023]. What is the connection between ASDYM reduction and KP reduction?

**Question 3:** KP equation, CBS (Calogero-Bogoyavlenskii-Schiff) equation, DS (Davey-Stewartson) equation are also famous (2+1)-d integrable systems. How to reduce ASDYM to these equations, while the soliton structure can be preserved?

**Thanks for Listening!**